L2 at Solar Maximum: Radiation Damage in the Euclid Space Telescope

eesa

UK SPACE

AGENCY

euclid

8th Radiation Damage Workshop 14th of May 2025



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Institute for Computational Cosmology In collaboration with Richard Massey, Gavin Leroy, Matt Wander, James Nightingale, et al.

Euclid



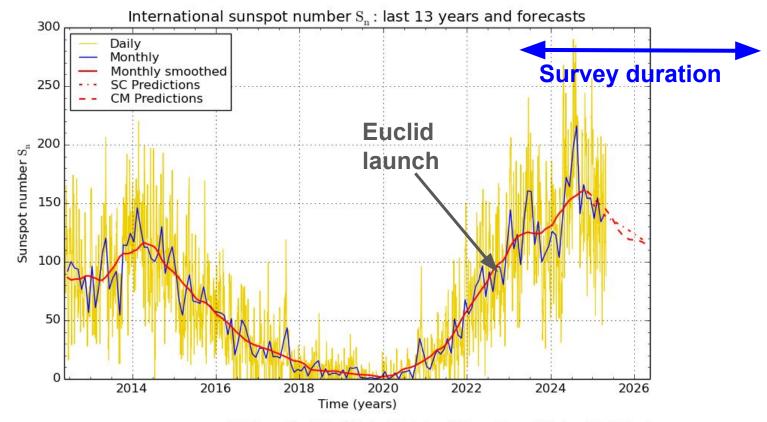
VIS instrument



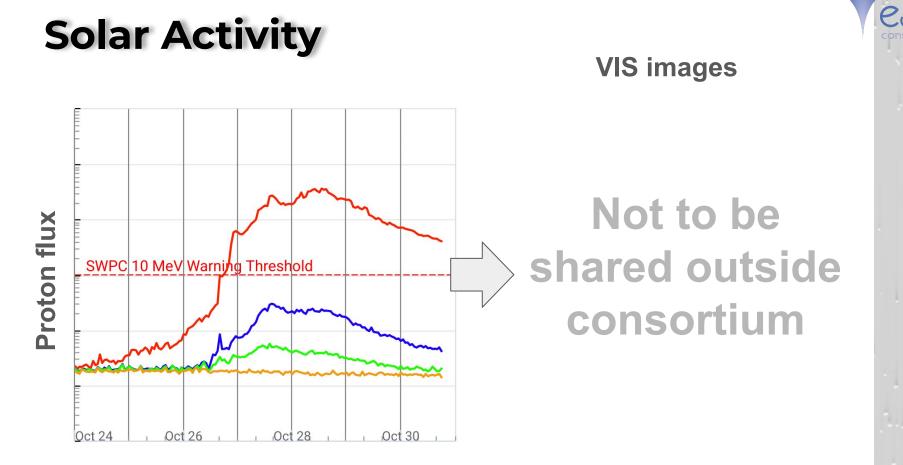




Solar Activity

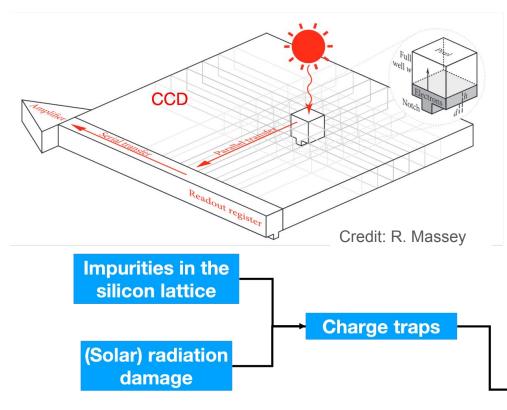


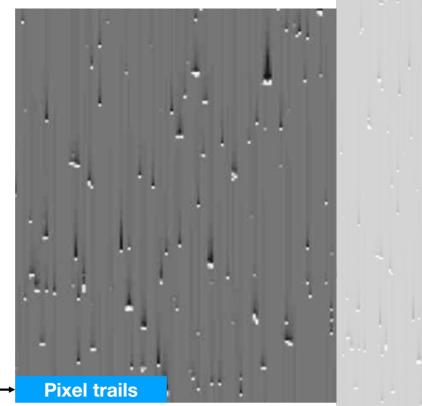
SILSO graphics (http://sidc.be/silso) Royal Observatory of Belgium 2025 May 1





Charge Transfer Inefficiency (CTI)



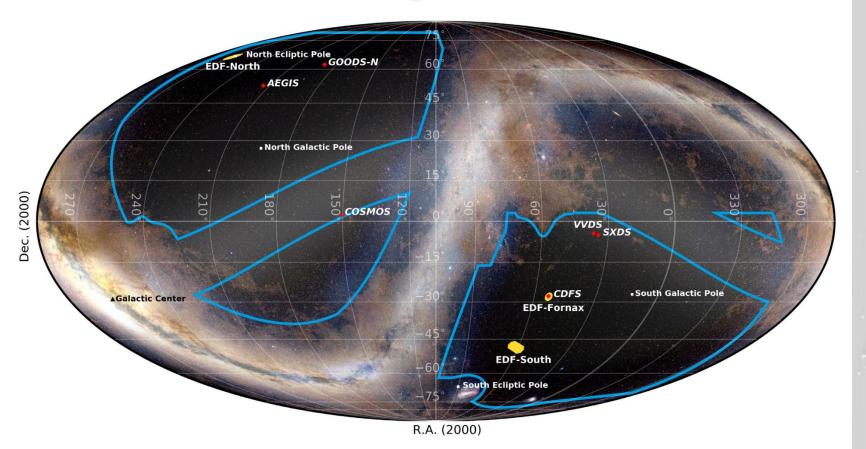




Charge Transfer Inefficiency (CTI)



Euclid Wide Survey





Euclid Wide Survey: Science

Euclid main science

- Weak gravitational lensing
- Galaxy clustering

Requires accurate

- Galaxy shapes
- Galaxy positions
- Galaxy redshifts

Euclid legacy science

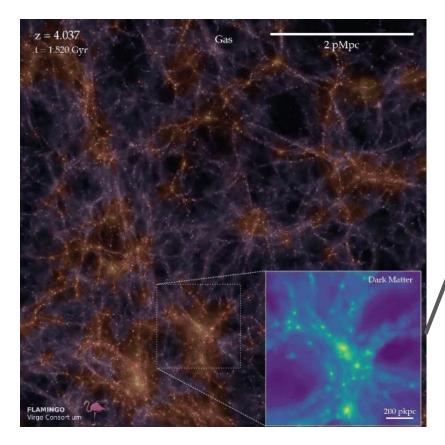
- Strong lensing
- Active Galactic Nuclei
- Galaxy evolution
- Transients
- Exoplanets etc.

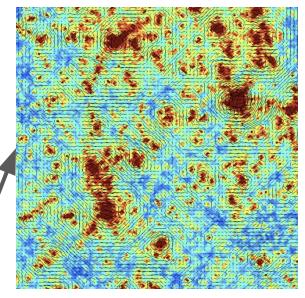
Requires accurate

- Photometry
- Astrometry etc.



Gravitational lensing



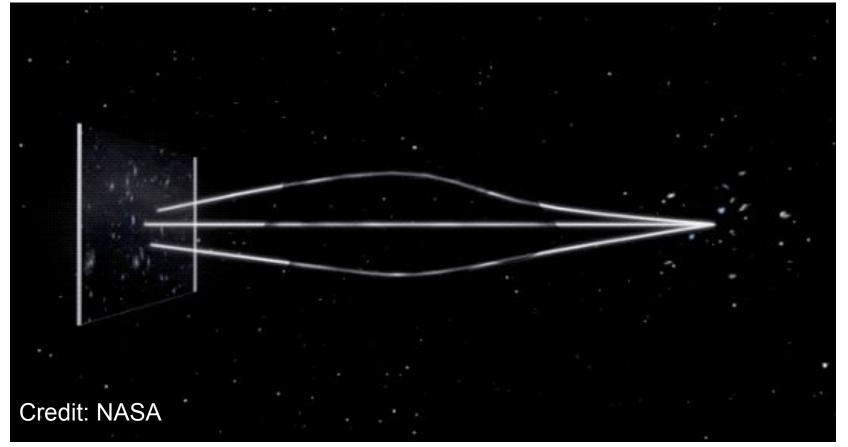


Probes the nature of:

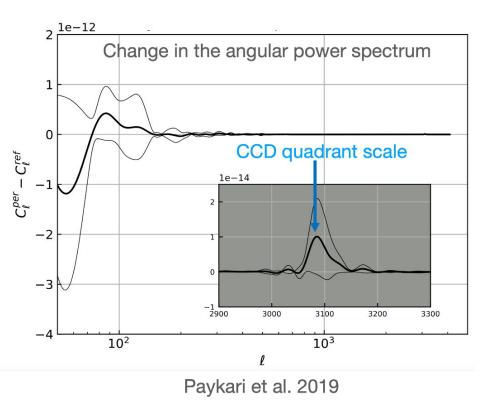
- Dark matter
- Dark energy
- Gravity



Gravitational lensing



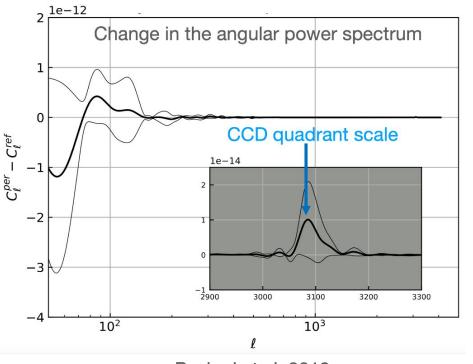
Why is CTI important?



As CTI distorts galaxy shapes, additional "structure" appears at CCD scales.



Why is CTI important?



Paykari et al. 2019

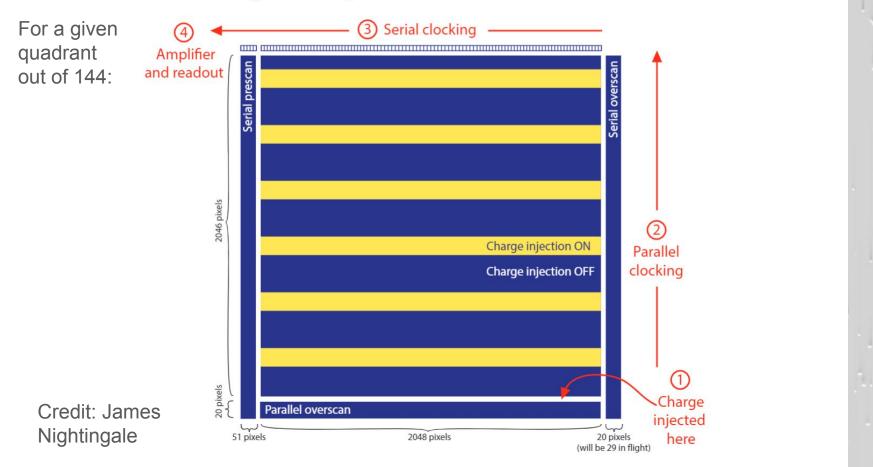
At these scales, other physically interesting effects may be detected:



+ other systematics



Data: Charge Injection Frames



Data: Charge Injection Frames



8 charge injection line (CIL) images are taken daily during the nominal survey

Cycle through 4 groups (A, B, C, D) of sets of 8 CILs with different patterns

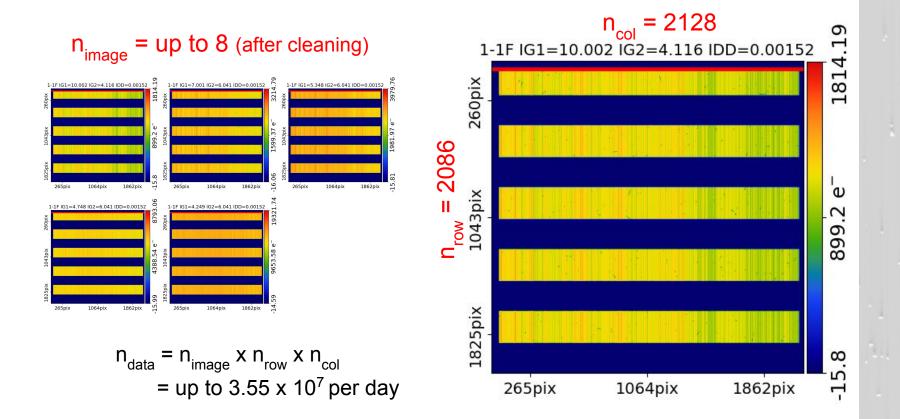
Cycle resets after 4 days

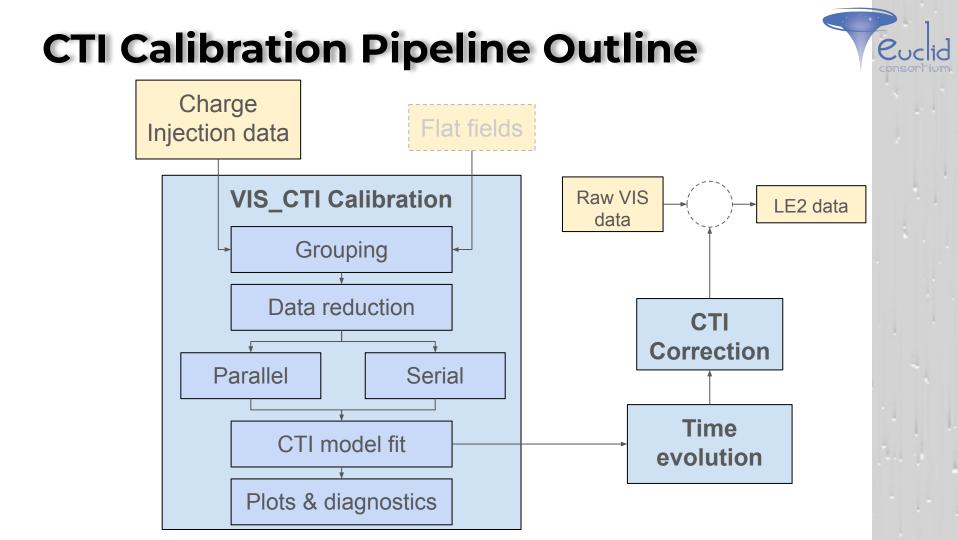
A given CTI model is calibrated on the data from a single group of up to 8 CILs

#Number	Day	Pattern	CHG_INJ_ON	CHG_INJ_OFF	ID_Delay [ms]	IG1 [V]	IG2 [V]	IG2- IG1 [V]	30us_DWELL(CHINJ_RoDly
1	1	CIR3	420	100	2.5	4.25	6	1.75	on
2	1	CIR1	214	200	2.5	4.75	6	1.25	on
3	1	CIR1	214	200	2.5	6.25	6	-0.25	on
4	1	CIR1	214	200	1.5	4.25	6	1.75	on
5	1	CIR1	214	200	1.5	4.75	6	1.25	on
6	1	CIR1	214	200	1.5	7	6	-1	on
7	1	CIR1	214	200	1.5	10	4	-6	on
8	1	CIR1	214	200	1.5	5.35	6	0.65	on
9	2	CIR1	214	200	1.5	4.75	6	1.25	OFF
10	2	CIR2	260	1500	2.5	4.75	6	1.25	on
11	2	CIR2	260	1500	2.5	6.25	6	-0.25	on
12	2	CIR2	260	1500	1.5	4.25	6	1.75	on
13	2	CIR2	260	1500	1.5	4.75	6	1.25	on
14	2	CIR2	260	1500	1.5	7	6	-1	on
15	2	CIR2	260	1500	1.5	10	4	-6	on
16	2	CIR2	260	1500	1.5	5.35	6	0.65	on
17	3	CIR3	420	100	2.5	4.25	6	1.75	on
18	3	CIR3	420	100	2.5	4.75	6	1.25	on
19	3	CIR3	420	100	2.5	6.25	6	-0.25	on
20	3	CIR3	420	100	1.5	4.25	6	1.75	on
21	3	CIR3	420	100	1.5	4.75	6	1.25	on
22	3	CIR3	420	100	1.5	7	6	-1	on
23	3	CIR3	420	100	1.5	10	4	-6	on
24	3	CIR3	420	100	1.5	5.35	6	0.65	on
25	4	CIR3	420	100	2.5	4.25	6	1.75	on
26	4	CIR2	260	1500	1.5	4.25	6	1.75	OFF
27	4	CIR4	53	50	2.5	6.25	6	-0.25	on
28	4	CIR4	53	50	1.5	4.25	6	1.75	on
29	4	CIR4	53	50	1.5	4.75	6	1.25	on
30	4	CIR4	53	50	1.5	5.35	6	0.65	on
31	4	CIR4	53	50	1.5	7	6	-1	on
32	4	CIR4	53	50	1.5	10	4	-6	on

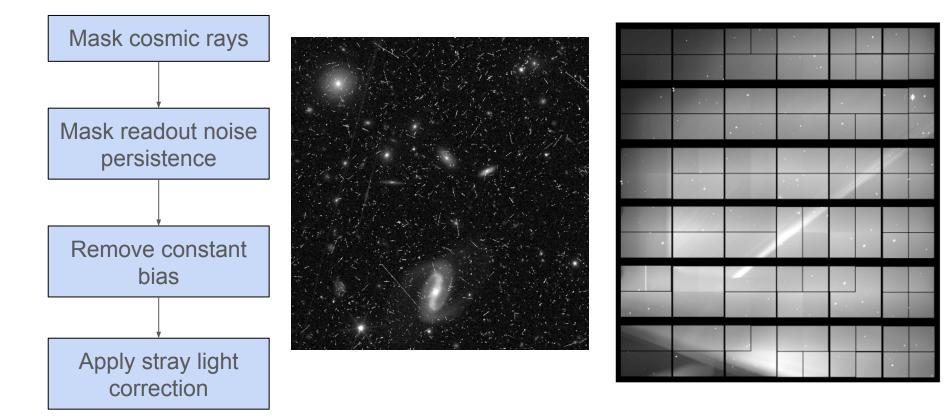
Data: Charge Injection Frames

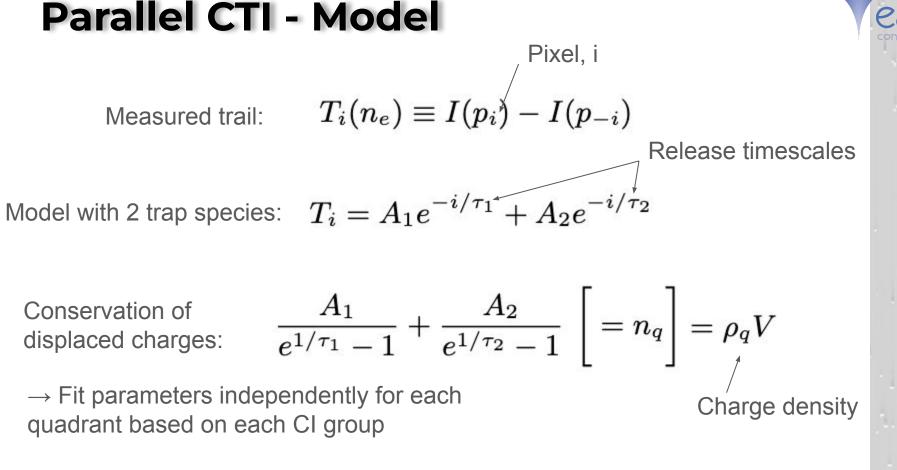






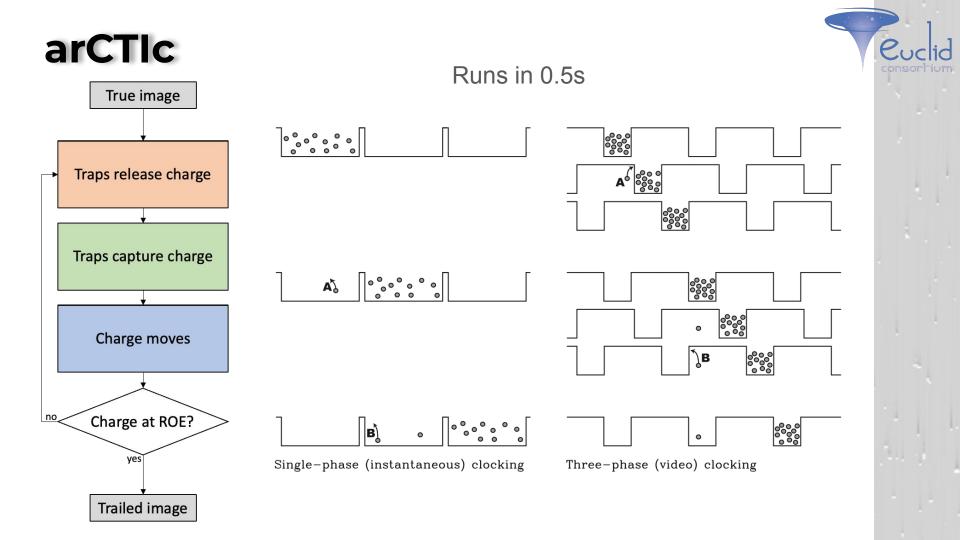
Data Preparation



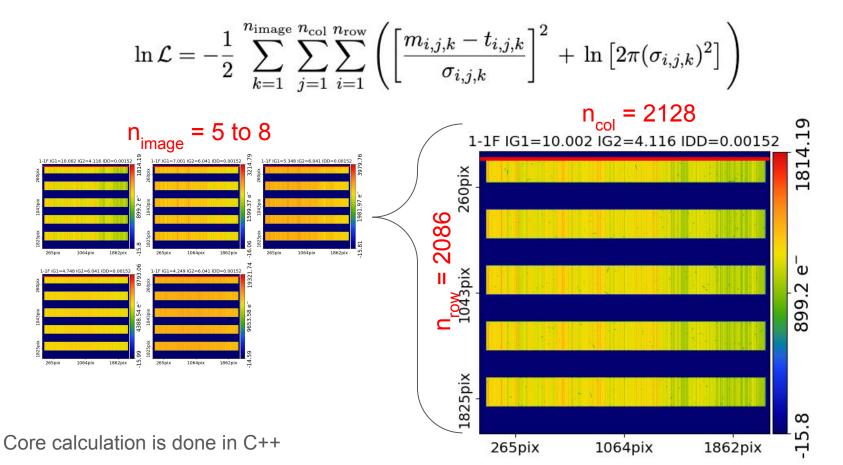


Modelled with arCTIc

arxiv:0909.0507



CTI Model Likelihood



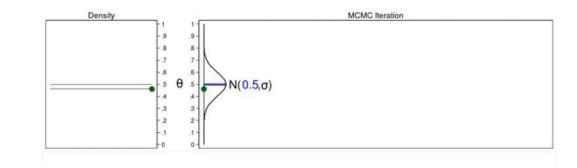


CTI Model Fitting

Bayesian Algorithms

- + Robust to overfitting
- + Incorporates prior knowledge (allowing for future computational savings)
- + Handles complex likelihoods well
- + Accurate up to 30 dimensions
- + Full uncertainty quantification
 - + Allows for rigorous testing
 - + Allows for time evolution pipeline (reducing necessary number of calibrations)

- Slow to converge
- Resource intensive















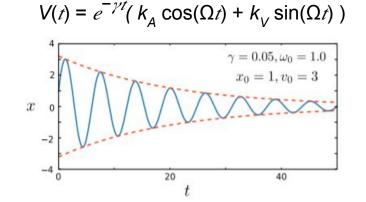
Absolute level of CTI

Relative change over 6 months



Serial CTI + Pixel Bounce - Model

Model with 2 trap species: $T_i = A_1 e^{-i/\tau_1} + A_2 e^{-i/\tau_2}$



 \rightarrow Fit parameters independently for each quadrant based on each CI group

Modelled with arCTIc

arxiv:0909.0507

Serial CTI - Model

During PV



Serial CTI - Model

6 months later



Serial CTI Calibration



Serial CTI Calibration



Summary

Euclid

• Euclid has been enjoying a nice Sun bath

• CTI in Euclid is lower than forecast, but uneven

• **CTI calibration is robust and scalable** (at least in parallel direction)

• Pixel bounce?

